

#### How to use the rivets



#### The Robotics Kit contains two types of rivet:

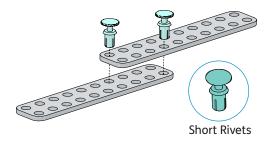


**Short Rivets** 



Long Rivets

#### Connecting 2 Build Plates



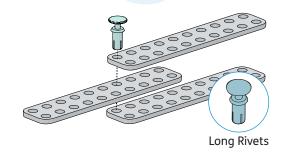








#### Connecting 3 Build Plates



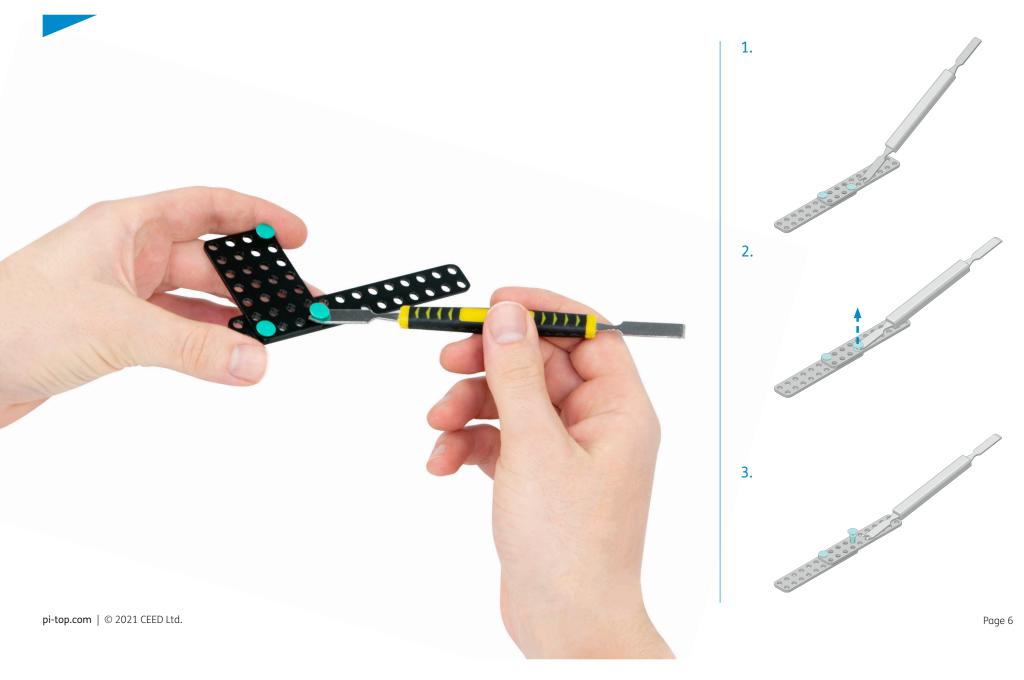
1.

2.

3.

4.

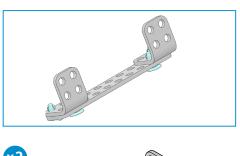
# **Using the Rivet Removal Tool**

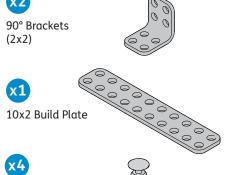


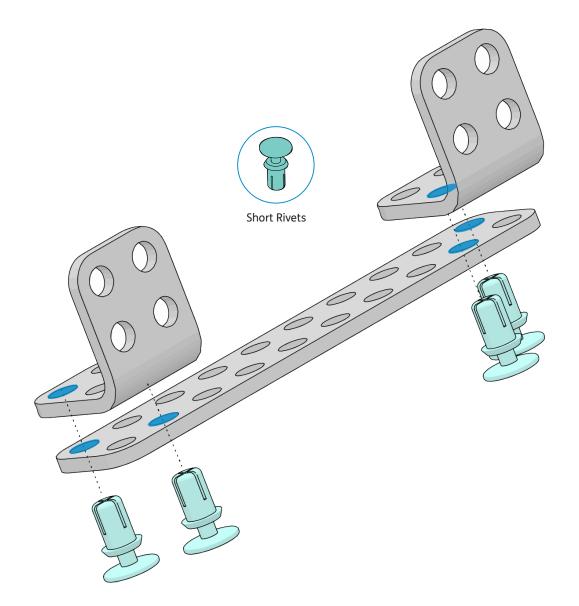
## Rear bumper

Part 1

Short Rivets

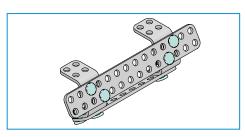


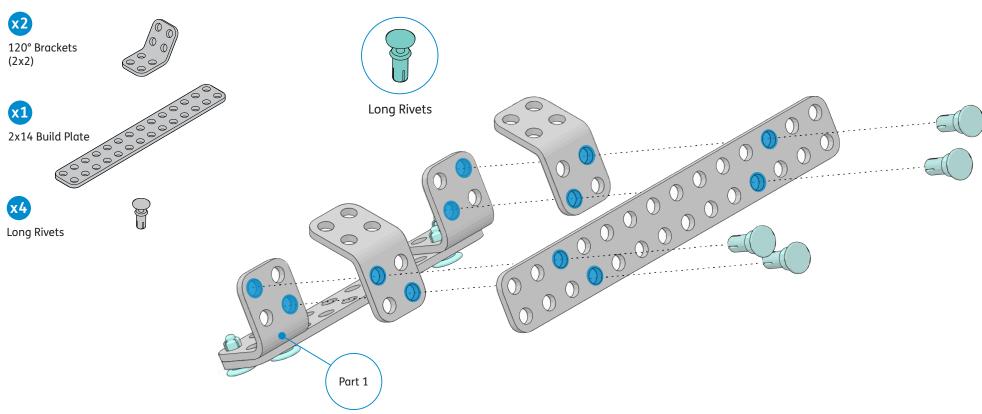




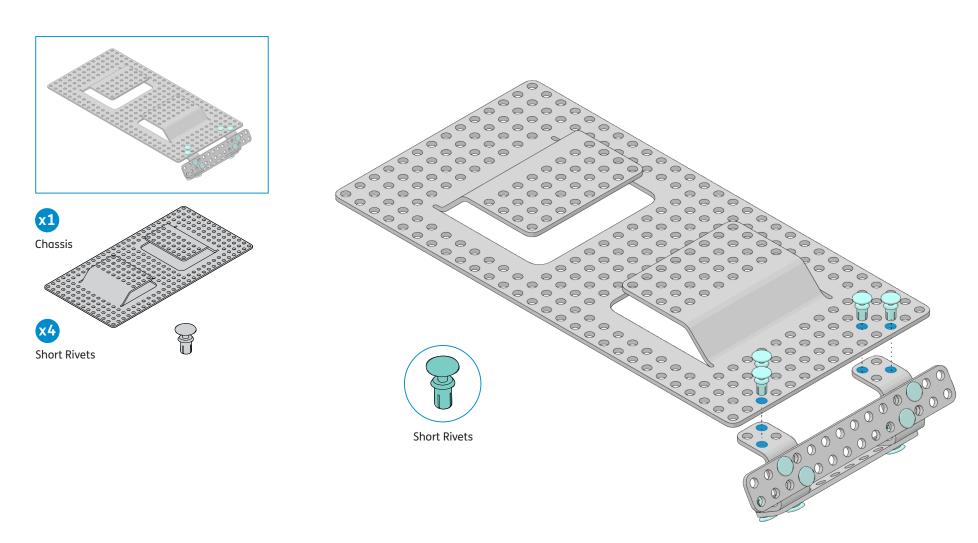
### **Rear bumper**

Part 2

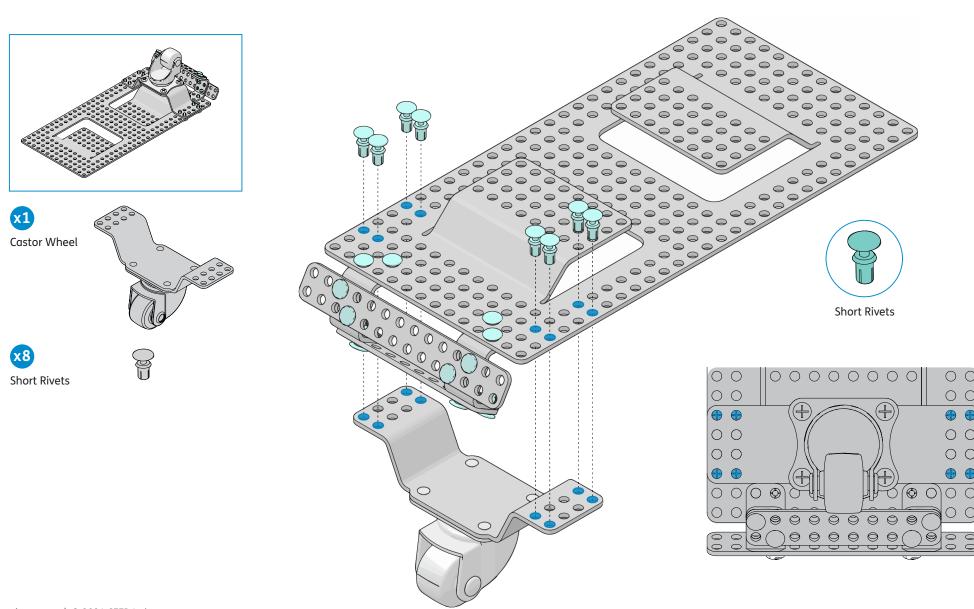




### Connecting the rear bumper to the chassis



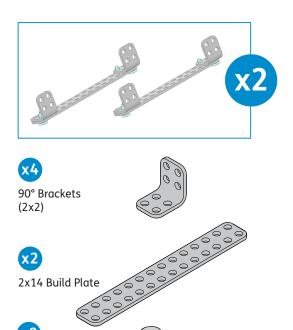
### Connecting the castor wheel to the chassis

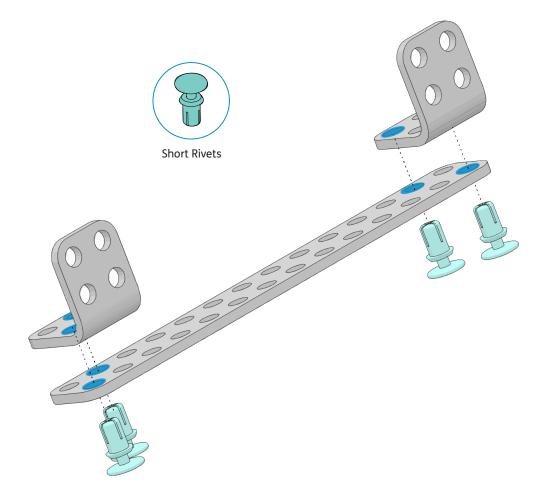


## **Side bumpers**

Part 1

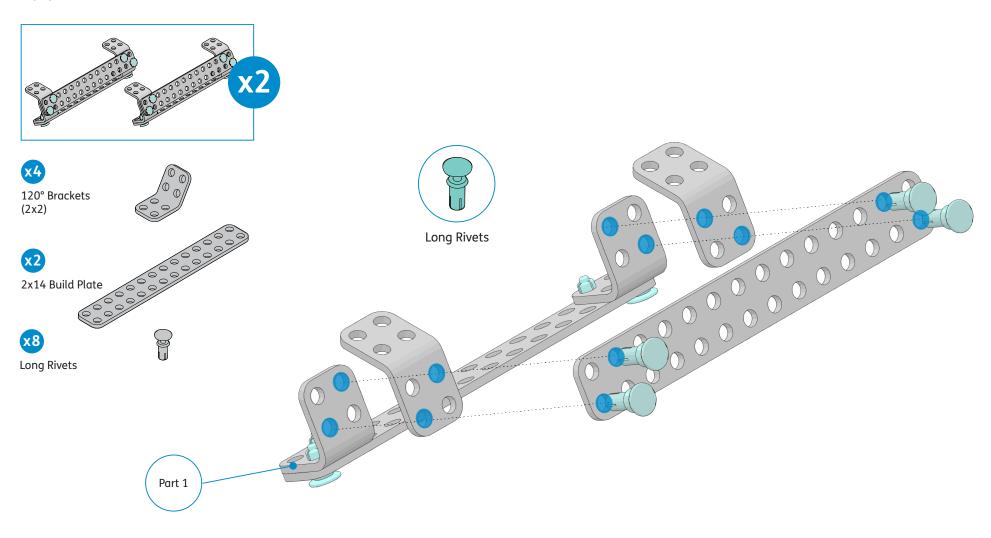
Short Rivets



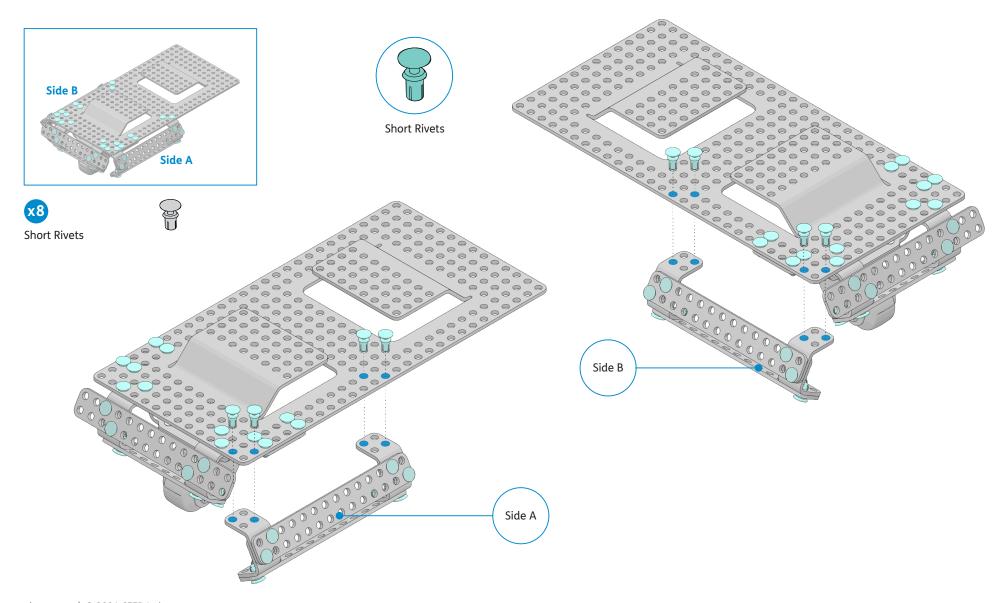


### **Side bumpers**

Part 2

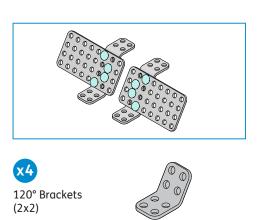


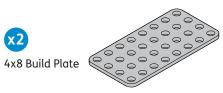
# Connecting the side bumpers to the chassis



## Front bumper

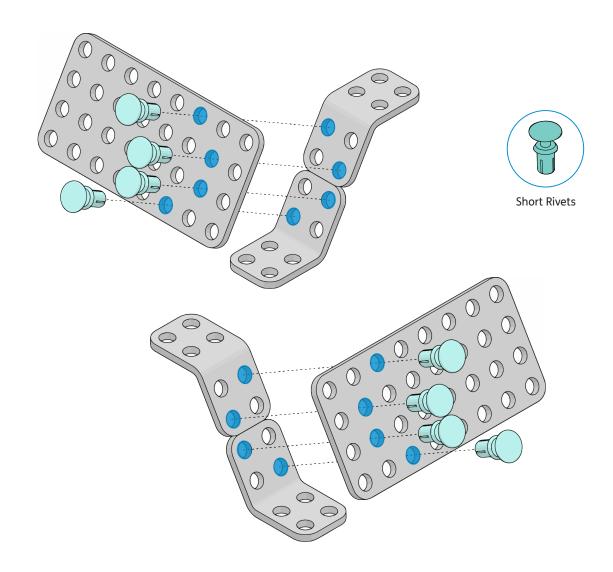
Part 1





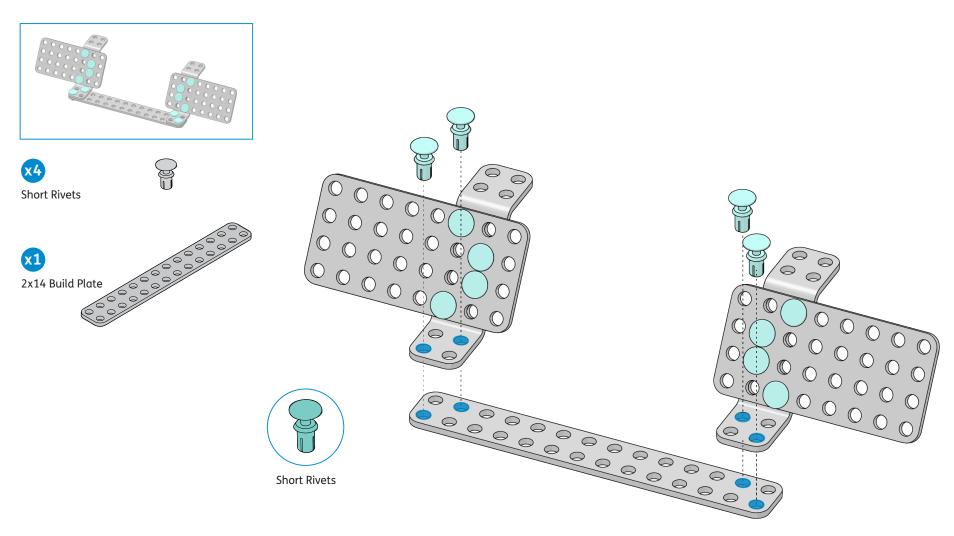




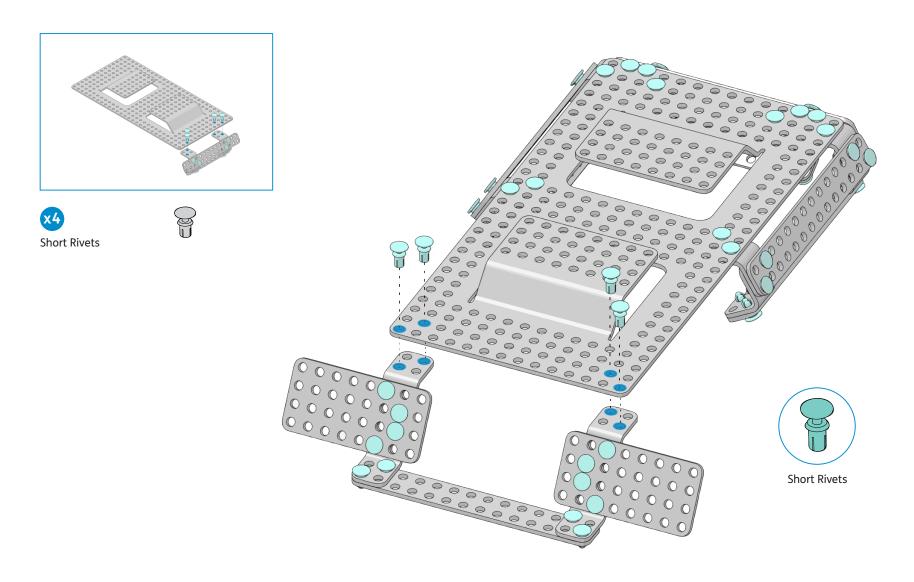


## **Front bumper**

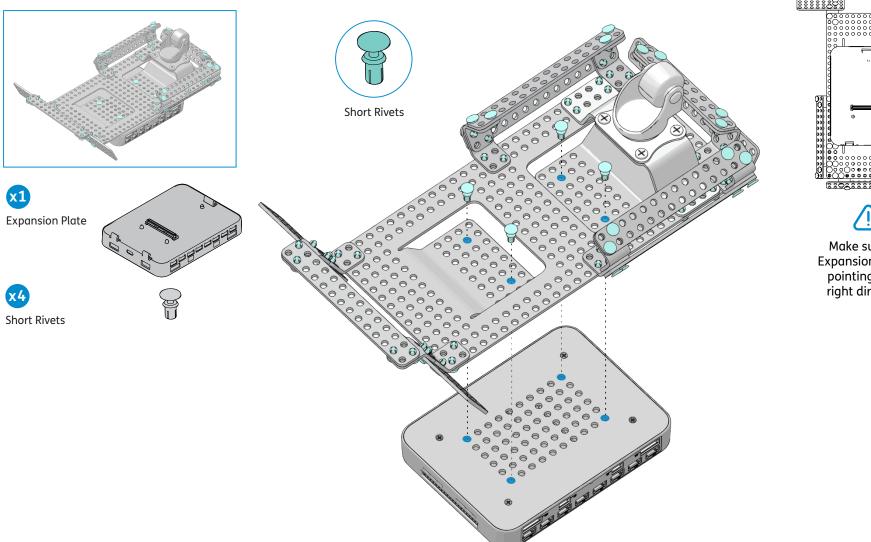
Part 2

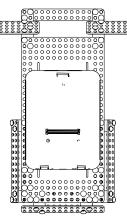


### Connecting the front bumper to the chassis



## **Expansion Plate**



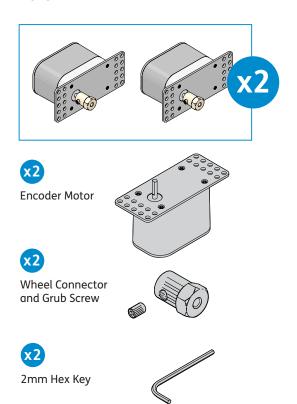


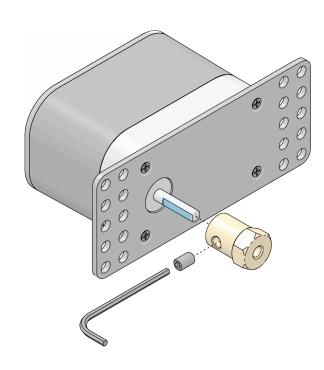


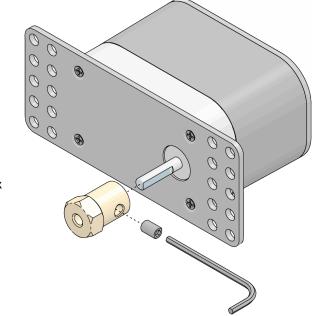
Make sure the Expansion Plate is pointing in the right direction!

#### **Encoder motors**

#### Part 1







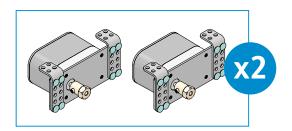
Make sure you align the flat edge of the

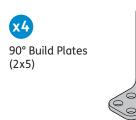
motor correctly to the Wheel Connector



### **Encoder motors**

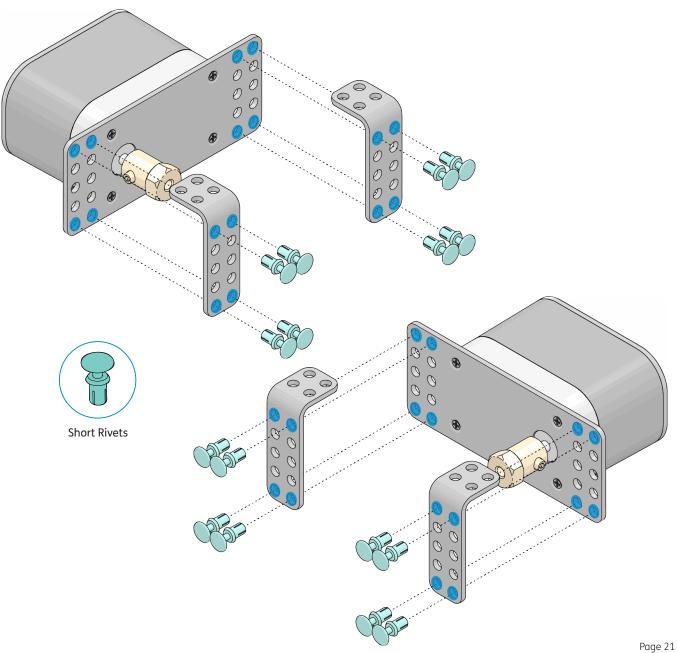
Part 2



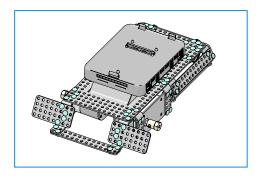






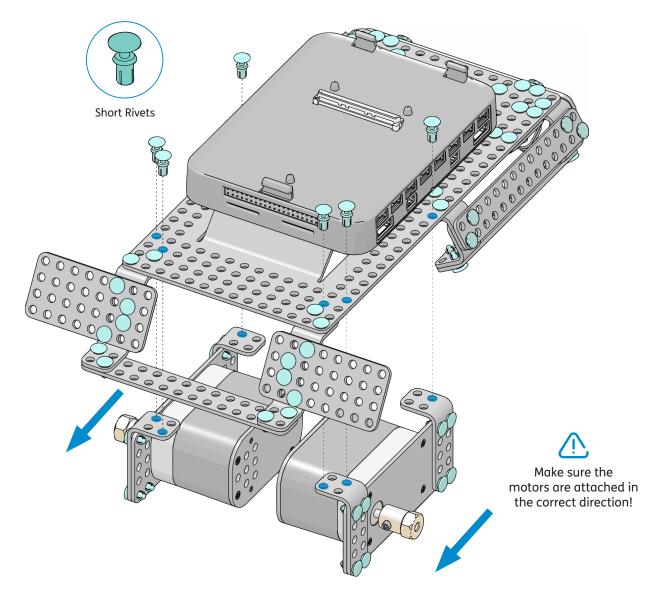


## **Motor** assembly

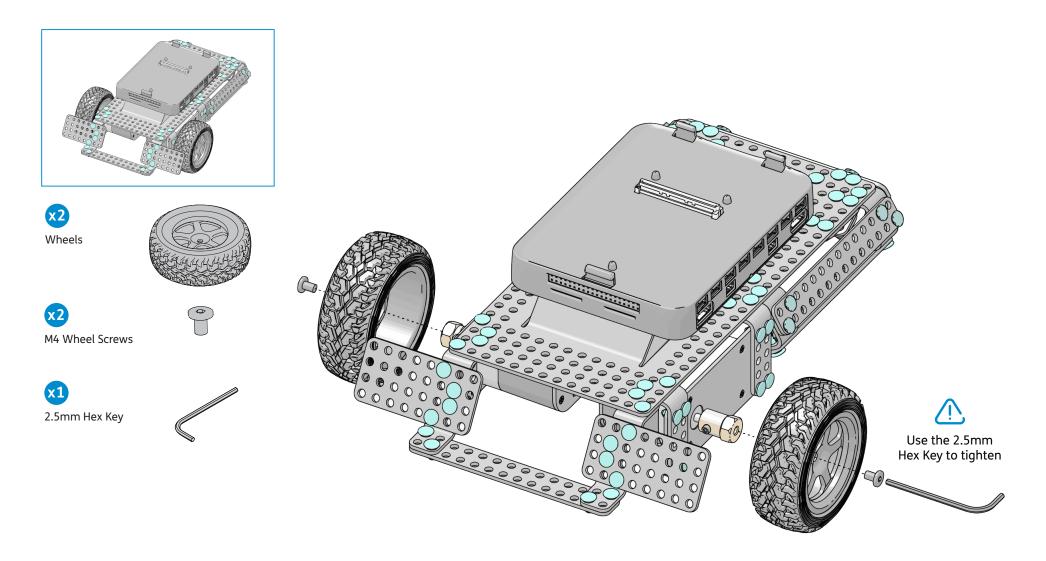




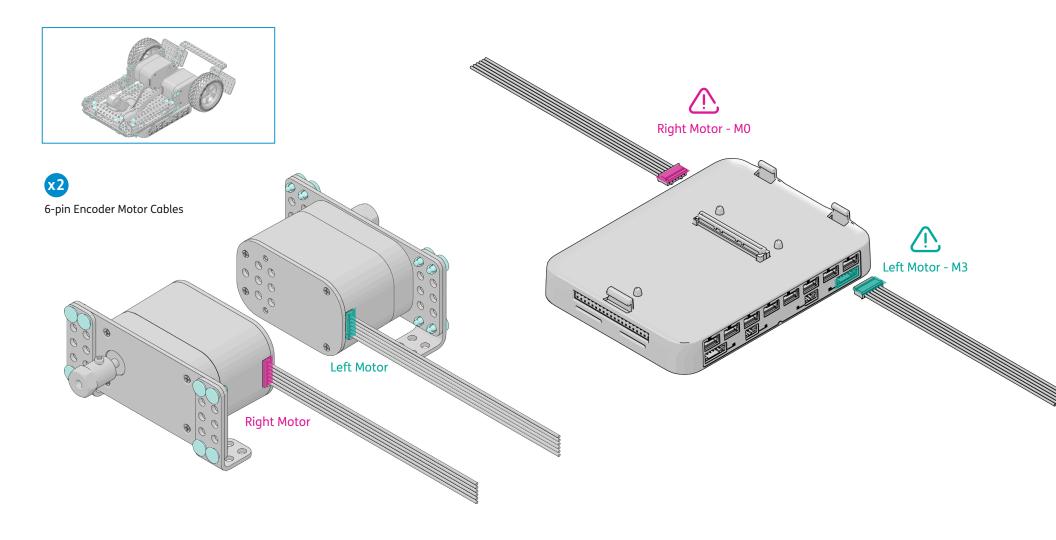




#### Wheels



## **Connecting the Encoder Motors**





Raspberry Pi made simple, robust and modular.

pi-top.com

Having trouble? Check out:

pi-top.com/support or forum.pi-top.com